

# Probability 1

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## Probability Spaces

A probability space is a triple  $(\Omega, \mathcal{F}, P)$  where  $\Omega$  is a set of “outcomes,”  $\mathcal{F}$  is a set of “events,” and  $P : \mathcal{F} \rightarrow [0, 1]$  is a function that assigns probabilities to events.

**Definition.** Let  $\Omega$  be a set. A nonempty collection  $\mathcal{F}$  of subsets of  $\Omega$  is called algebra (or field) if

(i) if  $A \in \mathcal{F}$  then  $\Omega \setminus A \in \mathcal{F}$ , and

(ii) if  $A, B \in \mathcal{F}$  then  $A \cup B \in \mathcal{F}$ .

$\mathcal{F}$  is called a  $\sigma$ -algebra (or  $\sigma$ -field)

if (i) (ii) and

(iii)  $A_1, A_2, \dots \in \mathcal{F} \implies \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ .

**Example.**  $\mathcal{F} = \{\emptyset, \Omega\}$  trivial  $\sigma$ -field

$\mathcal{F} = 2^{\Omega} = \{A \mid A \subset \Omega\}$  : power set  $\implies \sigma$ -field

**Example** ([1, Example 1.1.6]).  $\Omega = \mathbb{Z} = \{\text{integers}\}$ ,  $\mathcal{F} = \{A \subset \mathbb{Z} \mid |A| < \infty \text{ or } |A^c| < \infty\}$ . Then  $\mathcal{F}$  is a field but not a  $\sigma$ -field.

Without  $P$ ,  $(\Omega, \mathcal{F})$  is called a measurable space, i.e., it is a space on which we can put a measure.

**Definition.** A measure is a nonnegative countably additive set function; that is, for an  $\sigma$ -algebra  $\mathcal{F}$ , a function  $\mu : \mathcal{F} \rightarrow [0, \infty]$  is a measure if

(i)  $\mu(A) \geq \mu(\emptyset) = 0$  for all  $A \in \mathcal{F}$ , and

(ii) For  $A_1, A_2, \dots \in \mathcal{F}$  with  $A_i \cap A_j = \emptyset$  for any  $i \neq j$ ,

$$\mu\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} \mu(A_i).$$

**Definition.** (1)  $\mu(\Omega) < \infty \implies$  finite measure

(2)  $\mu(\Omega) = 1 \implies$  probability measure

(3)  $\exists$  a partition  $A_1, A_2, \dots$  with  $\bigcup_{i=1}^{\infty} A_i = \Omega$  and  $\mu(A_i) < \infty \implies \sigma$ -finite measure

**Theorem** ([1, Theorem 1.1.1]). Let  $\mu$  be a measure on  $(\Omega, \mathcal{F})$ .

(i) *Monotonicity.* If  $A \subset B$  then  $\mu(A) \leq \mu(B)$ .

(ii) *Subadditivity.* If  $A \subset \bigcup_{i=1}^{\infty} A_i$  then  $\mu(A) \leq \sum_{i=1}^{\infty} \mu(A_i)$ .

(iii) *Continuity from below.*  $A_n \uparrow A$  ( i.e.  $A_1 \subset A_2 \subset \dots$  and  $A = \bigcup_{i=1}^{\infty} A_i$ ) then  $\mu(A_i) \uparrow \mu(A)$ .

(iv) *Continuity from above.*  $A_n \downarrow A$  ( i.e.  $A_1 \supset A_2 \supset \dots$  and  $A = \bigcap_{i=1}^{\infty} A_i$ ) with  $\mu(A_1) < \infty$  then  $\mu(A_i) \downarrow \mu(A)$ .

**Definition.** Let  $\mathcal{A}$  be a class of subsets of  $\Omega$ . Then  $\sigma(\mathcal{A})$  denotes the smallest  $\sigma$ -algebra that contains  $\mathcal{A}$ .

For any  $\mathcal{A}$ , such  $\sigma(\mathcal{A})$  exists and is unique: this is by the following:

- (i) If  $\mathcal{F}_i, i \in I$  are  $\sigma$ -fields, then  $\bigcap_{i \in I} \mathcal{F}_i$  is a  $\sigma$ -field.
- (ii) If we are given a collection  $\mathcal{A}$  of subsets of  $\Omega$ , then there is a smallest  $\sigma$ -field containing  $\mathcal{A}$ .

**Definition.** Borel  $\sigma$ -field on  $\mathbb{R}^d$ , denoted by  $\mathcal{R}^d$ , is the smallest  $\sigma$ -field containing all open sets.

**Theorem** ([1, Theorem 1.1.4]). *There is a unique measure  $\mu$  on  $(\mathbb{R}, \mathcal{R})$  with*

$$\mu((a, b]) = b - a.$$

*Such measure is called Lebesgue measure.*

## Distribution and Random Variables

**Definition.** Let  $(\Omega, \mathcal{F})$  and  $(S, \mathcal{S})$  are measurable spaces. A mapping  $X : \Omega \rightarrow S$  is a measurable map from  $(\Omega, \mathcal{F})$  to  $(S, \mathcal{S})$  if

$$\text{for all } B \in \mathcal{S}, X^{-1}(B) := \{\omega \in \Omega : X(\omega) \in B\} \in \mathcal{F}.$$

If  $(S, \mathcal{S}) = (\mathbb{R}^d, \mathcal{R}^d)$  (where  $\mathcal{R}^d = \mathcal{B}(\mathbb{R}^d)$ ) and  $d > 1$  then  $X$  is called a random vector. If  $d = 1$ ,  $X$  is called a random variable.

For convenience, we sometimes replace  $\mathbb{R}^d$  by  $(\mathbb{R}^*)^d = [-\infty, \infty]^d$  and  $(\mathcal{R}^*)^d = \mathcal{B}((\mathbb{R}^*)^d)$  and still say random vector (or random variable).

**Example.** A trivial but useful example of a random variable is indicator function  $1_A$  of a set  $A \in \mathcal{F}$ :

$$1_A(\omega) = \begin{cases} 1 & \omega \in A, \\ 0 & \omega \notin A. \end{cases}$$

If  $X$  is a random variable, then  $X$  induces a probability measure on  $\mathbb{R}$ .

**Definition.** The probability measure  $\mu$  on  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$  defined as  $\mu(A) = P(X \in A)$  for all  $A \in \mathcal{B}(\mathbb{R})$  is called the distribution of  $X$ .

*Remark.* The distribution can be defined similarly for random vectors.

The distribution of a random variable  $X$  is usually described by giving its distribution function.

**Definition.** The distribution function  $F(x)$  of a random variable  $X$  is defined as  $F(x) = P(X \leq x)$ .

**Theorem** ([1, Theorem 1.2.1]). *Any distribution function  $F$  has the following properties:*

- (i)  $F$  is nondecreasing.
- (ii)  $\lim_{n \rightarrow \infty} F(x) = 1, \lim_{n \rightarrow -\infty} F(x) = 0$ .
- (iii)  $F$  is right continuous. i.e.  $\lim_{y \downarrow x} F(y) = F(x)$ .
- (iv)  $P(X < x) = F(x-) = \lim_{y \uparrow x} F(y)$ .
- (v)  $P(X = x) = F(x) - F(x-)$ .

**Theorem** ([1, Theorem 1.2.2]). *If  $F$  satisfies (i) (ii) (iii) in [1, Theorem 1.2.1], then it is the distribution function of some random variable. That is, there exists a triple  $(\Omega, \mathcal{F}, P)$  and a random variable  $X$  such that  $F(x) = P(X \leq x)$ .*

**Theorem.** If  $F$  satisfies (i) (ii) (iii), then there uniquely exists a probability measure  $\mu$  on  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$  such that for all  $a < b$ ,

$$\mu((a, b]) = F(b) - F(a).$$

**Definition.** If  $X$  and  $Y$  induce the same distribution  $\mu$  on  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ , we say  $X$  and  $Y$  are equal in distribution. We write

$$X \stackrel{d}{=} Y.$$

**Definition.** When the distribution function  $F(x) = P(X \leq x)$  has the form  $F(x) = \int_{-\infty}^x f(y)dy$ , then we say  $X$  has the density function  $f$ .

*Remark.*  $f$  is not unique, but unique up to Lebesgue measure 0.

*Remark.* For defining a density function of a given probability measure, we can use the Radon-Nykodym Theorem.

**Definition.** If  $F$  has a property that there exists  $f$  such that  $F(x) = \int_{-\infty}^x f(y)dy$ , we call  $F$  is absolutely continuous.

**Example** ([1, Example 1.2.7]). Uniform distribution on the Cantor set

Let  $C_0 := [0, 1]$ , and let  $C_{n+1}$  be defined by removing middle third open interval of each interval that remains. For example,  $C_1 = [0, \frac{1}{3}] \cup [\frac{2}{3}, 1]$ .

Let  $\mathcal{C} := \bigcap_{n=0}^{\infty} C_n$  : Cantor set.

Let  $F_0 : [0, 1] \rightarrow \mathbb{R}$  by  $F_0(x) = x$

$$\text{Let } F_{n+1} : [0, 1] \rightarrow \mathbb{R} \text{ by } F_{n+1}(x) = \begin{cases} \frac{1}{2}F_n(x) & 0 \leq x \leq \frac{1}{3} \\ \frac{1}{2} & \frac{1}{3} \leq x \leq \frac{2}{3} \\ \frac{1}{2} + \frac{1}{2}F_n(3x - 2) & \frac{2}{3} \leq x \leq 1 \end{cases}$$

Then,  $\{F_n\}$  are uniformly Cauchy, so it converges to a continuous function  $F : [0, 1] \rightarrow \mathbb{R}$

$F$  is constant on each excluded middle interval, so if  $\exists f$  s.t.  $\int_0^x f(t)dt = F(x)$ ,  $f = 0$  on  $\mathcal{C}^C$

This is impossible because Cantor set has measure 0

**Example** ([1, Example 1.2.9]). Dense discontinuities. Let  $q_1, q_2, \dots$  be an enumeration of the rationals. Let  $\alpha_i > 0$  with  $\sum_{i=1}^{\infty} \alpha_i = 1$  and let

$$F(x) = \sum_{i=1}^{\infty} \alpha_i 1_{[q_i, \infty)}$$

**Exercise** ([1, Exercise 1.2.3]). Show that the number of jumps of distribution is at most countable.

**Theorem** ([1, Theorem 1.3.1]). Let  $\mathcal{A}$  be a collection of sets in  $\mathcal{S}$  such that

(i)  $\{\omega \mid X(\omega) \in A\} \in \mathcal{F}$  for all  $A \in \mathcal{A}$

(ii)  $\sigma(\mathcal{A}) = \mathcal{S}$

Then  $X$  is measurable.

*Remark.* Note that  $\{\{X \in B\} \mid B \in \mathcal{S}\}$  is a  $\sigma$ -field. It is the smallest  $\sigma$ -field on  $\Omega$  that makes  $X$  a measurable map.

It is called the  $\sigma$ -field generated by  $X$  and denoted by  $\sigma(X)$

**Example** ([1, Exercise 1.3.2]).  $(S, \mathcal{S}) = (\mathbb{R}, \mathcal{R})$ . Possible choices of  $\mathcal{A}$  in Theorem 1.3.1 are

$$\mathcal{A} = \begin{cases} \{(-\infty, x] \mid x \in \mathbb{R}\} \\ \{(-\infty, x) \mid x \in \mathbb{R}\} \\ \{(-\infty, x] \mid x \in \mathbb{Q}\} \\ \{(-\infty, x) \mid x \in \mathbb{Q}\} \end{cases}$$

**Example** ([1, Exercise 1.3.3]).  $(S, \mathcal{S}) = (\mathbb{R}^d, \mathcal{R}^d)$ . A useful choice of  $\mathcal{A}$  in Theorem 1.3.1 is

$$\{(a_1, b_1) \times \cdots \times (a_d, b_d) \mid -\infty < a_i < b_i < \infty\} \text{ (set of open rectangles)}$$

**Theorem** ([1, Theorem 1.3.4]). *If  $X : (\Omega, \mathcal{F}) \rightarrow (S, \mathcal{S})$  and  $f : (S, \mathcal{S}) \rightarrow (T, \mathcal{T})$  are measurable maps, then  $f(X)$  is measurable.*

**Theorem.**  *$f : (S, \mathcal{S}) \rightarrow (T, \mathcal{T})$  and suppose  $\mathcal{S} = \sigma(\text{open sets})$ ,  $\mathcal{T} = \sigma(\text{open sets})$ . Then, if  $f$  is continuous then  $f$  is measurable.*

**Theorem** ([1, Theorem 1.3.5]). *If  $X_1, \dots, X_n$  are random variables and  $f : (\mathbb{R}^n, \mathcal{R}^n) \rightarrow (\mathbb{R}, \mathcal{R})$  is measurable, then  $f(X_1, \dots, X_n)$  is a random variable.*

**Theorem** ([1, Theorem 1.3.6]). *If  $X_1, \dots, X_n$  are random variables then  $X_1 + \cdots + X_n$  is a random variable.*

*Remark.* If  $X, Y$  are random variables, then

$$cX \text{ (} c \text{ is scalar), } X \pm Y, XY, \sin(X), X^2, \dots,$$

are all random variables.

**Theorem** ([1, Theorem 1.3.7]).  *$\inf_n X_n, \sup_n X_n, \limsup_n X_n, \liminf_n X_n$  are random variables.*

## Integration and Expectation

Let  $\mu$  be a  $\sigma$ -finite measure on  $(\Omega, \mathcal{F})$ .

**Definition.** For any predicate  $Q(\omega)$  defined on  $\Omega$ , we say  $Q$  is true  $(\mu-)$ almost everywhere (or a.e.) if  $\mu(\{\omega : Q(\omega) \text{ is false}\}) = 0$

**Step 1.**

**Definition.**  $\varphi$  is a simple function if  $\varphi(\omega) = \sum_{i=1}^n a_i 1_{A_i}$  with  $A_i \in \mathcal{F}$

If  $\varphi$  is a simple function and  $\varphi \geq 0$ , we let

$$\int \varphi d\mu = \sum_{i=1}^n a_i \mu(A_i)$$

**Step 2.**

**Definition.** If  $f$  is measurable and  $f \geq 0$  then we let

$$\int f d\mu = \sup \left\{ \int \varphi d\mu : 0 \leq \varphi \leq f \text{ and } \varphi \text{ simple} \right\}$$

We define the integral of  $f$  over the set  $E$ :

$$\int_E f d\mu := \int f \cdot 1_E d\mu$$

**Step 3.**

**Definition.** We say measurable  $f$  is integrable if  $\int |f| d\mu < \infty$ . Let

$$f^+(x) := f(x) \vee 0, \quad \text{and} \quad f^-(x) := (-f(x)) \vee 0,$$

where  $a \vee b = \max(a, b)$ . We define the integral of  $f$  by

$$\int f d\mu = \int f^+ d\mu - \int f^- d\mu.$$

we can also define  $\int f d\mu$  if  $\int f^+ d\mu = \infty$  and  $\int f^- d\mu < \infty$ , or  $\int f^+ d\mu < \infty$  and  $\int f^- d\mu = \infty$

**Theorem** ([1, Theorem 1.4.7]). *Suppose  $f$  and  $g$  are integrable.*

- (i) *If  $f \geq 0$  a.e. then  $\int f d\mu \geq 0$*
- (ii)  $\forall a \in \mathbb{R}, \int a f d\mu = a \int f d\mu$
- (iii)  $\int f + g d\mu = \int f d\mu + \int g d\mu$
- (iv) *If  $g \leq f$  a.e. then  $\int g d\mu \leq \int f d\mu$*
- (v) *If  $g = f$  a.e. then  $\int g d\mu = \int f d\mu$*
- (vi)  $|\int f d\mu| \leq \int |f| d\mu$

**Definition.**  $\|f\|_p = (\int |f|^p d\mu)^{1/p}$  for  $0 < p < \infty$

$$\|f\|_\infty = \inf\{M : \mu(\{x : |f(x)| > M\}) = 0\}$$

Notice that  $\forall c \in \mathbb{R}, \|cf\|_p = |c| \cdot \|f\|_p$

**Theorem** ([1, Theorem 1.5.1]). *Jensen's inequality. Suppose  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  is convex, that is, for all  $\lambda \in [0, 1]$  and  $x, y \in \mathbb{R}$ ,*

$$\lambda\varphi(x) + (1 - \lambda)\varphi(y) \geq \varphi(\lambda x + (1 - \lambda)y).$$

*If  $\mu$  is a probability measure, and  $f$  and  $\varphi(f)$  are integrable, then*

$$\varphi\left(\int f d\mu\right) \leq \int \varphi(f) d\mu.$$

**Theorem** ([1, Theorem 1.5.2]). *Holder's inequality. If  $p, q \in [1, \infty]$  with  $1/p + 1/q = 1$ , then*

$$\int |fg| d\mu \leq \|f\|_p \|g\|_q.$$

*Remark.* The special case  $p = q = 2$  is called the Cauchy-Schwarz inequality

**Definition.** We say  $f_n \rightarrow f$  in measure if  $\forall \epsilon > 0, \lim_{n \rightarrow \infty} \mu\{x : |f_n(x) - f(x)| > \epsilon\} = 0$

**Theorem** ([1, Theorem 1.5.3]). *Bounded convergence theorem. Let  $E$  be a set with  $\mu(E) < \infty$ . Suppose  $f_n$  vanishes on  $E^c$ ,  $|f_n(x)| \leq M$ , and  $f_n \rightarrow f$  in measure. Then*

$$\int f d\mu = \lim_{n \rightarrow \infty} \int f_n d\mu.$$

**Theorem** ([1, Theorem 1.5.5]). *Fatou's lemma. If  $f_n \geq 0$  then*

$$\liminf_n \int f_n d\mu \geq \int \left(\liminf_n f_n\right) d\mu.$$

**Theorem** ([1, Theorem 1.5.7]). *Monotone convergence theorem. If  $f_n \geq 0$  and  $f_n \uparrow f$  then*

$$\int f_n d\mu \uparrow \int f d\mu.$$

**Theorem** ([1, Theorem 1.5.8]). *Dominated convergence theorem. If  $f_n \rightarrow f$  a.e.,  $|f_n| \leq g$  for all  $n$ , and  $g$  is integrable, then*

$$\int f_n d\mu \rightarrow \int f d\mu.$$

**Definition.** If  $X$  is a random variable on  $(\Omega, \mathcal{F}, P)$ , we define its expected value to be  $\mathbb{E}(X) = \int_{\Omega} X dP$

We also write  $\mathbb{E}(X; A) = \int_A X dP$ .

**Theorem** ([1, Theorem 1.6.4]). *Chebyshev's inequality. Suppose  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  has  $\varphi \geq 0$ , let  $A \in \mathcal{R}$  and let  $i_A = \inf\{\varphi(y) : y \in A\}$*

$$i_A P(X \in A) \leq \mathbb{E}(\varphi(X); X \in A) \leq \mathbb{E}\varphi(X)$$

*Remark.* if  $\varphi(x) = x^2$  and  $A = \{x : |x| \geq a\}$ :

$$a^2 P(|X| \geq a) \leq \mathbb{E}X^2.$$

## Several techniques of integration

- The pushforward measure of a transformation  $T$  is  $T_*\mu := \mu(T^{-1}(A))$ . The change of variables formula for pushforward measures is

$$\int_{\Omega} f \circ T d\mu = \int_{T(\Omega)} f dT_*\mu.$$

Now, consider a probability space  $(\Omega, \mathcal{F}, P)$ , and consider a measurable map  $X : (\Omega, \mathcal{F}) \rightarrow (S, \mathcal{S})$  as a transformation. Then the distribution measure  $\mu_X$  of  $X$  is in fact the pushforward measure  $\mu_X(A) = P(X \in A) = P(X^{-1}(A))$ , and hence the change of variable formula becomes

$$\mathbb{E}_P[f(X)] = \int_{\Omega} f(X(\omega)) dP(\omega) = \int_{X(\Omega)} f(x) d\mu_X(x).$$

- For Lebesgue measure  $\lambda$  and Riemann integrable function  $f$ ,  $\int_{[a,b]} f d\lambda$  is the same as the Riemann integral  $\int_a^b f(x) dx$ .
- $\int f d\delta_x = f(x)$ , where  $\delta_x$  is the Dirac-delta measure, i.e.,  $\delta_x(A) = I(x \in A)$ .
- For a random variable  $X \geq 0$ ,

$$\begin{aligned} \mathbb{E}_P[X] &= \int_{\Omega} X(\omega) dP(\omega) = \int_{\Omega} \int_{[0, X(\omega)]} dt dP(\omega) \\ &= \int_{\{(\omega, t) \in \Omega \times [0, \infty) : 0 \leq t \leq X(\omega)\}} dt \times dP(\omega) \\ &= \int_0^{\infty} \int_{\{\omega \in \Omega : X(\omega) \geq t\}} dP(\omega) dt \\ &= \int_0^{\infty} P(X \geq t) dt. \end{aligned}$$

## Product Measures, Fubini's Theorem

Let  $\{(\Omega_i, \mathcal{F}_i, \mu_i)\}_{i=1}^n$  be a sequence of  $\sigma$ -finite measure spaces.

Let  $\Omega = \Omega_1 \times \cdots \times \Omega_n = \{(\omega_1, \dots, \omega_n) \mid \omega_i \in \Omega_i\}$

Let  $\mathcal{F} = \mathcal{F}_1 \times \cdots \times \mathcal{F}_n$  = the  $\sigma$ -field generated by  $A_1 \times \cdots \times A_n$ , where  $A_i \in \mathcal{F}_i$

Then there exists a unique measure  $\mu$  on  $\mathcal{F}$  with

$$\mu(A_1 \times \cdots \times A_n) = \mu_1(A_1) \cdots \mu_n(A_n).$$

Let  $(X, \mathcal{A}, \mu_1)$  and  $(Y, \mathcal{B}, \mu_2)$  be two  $\sigma$ -finite measure spaces. Let  $\mu = \mu_1 \times \mu_2$ .

**Theorem** ([1, Theorem 1.7.2]). *Fubini's theorem.* Let  $f$  be a measurable function. If  $f \geq 0$  or  $\int |f| d\mu < \infty$ , then

$$\int_X \int_Y f(x, y) \mu_2(dy) \mu_1(dx) = \int_{X \times Y} f d\mu = \int_Y \int_X f(x, y) \mu_1(dx) \mu_2(dy)$$

**Example** ([1, Example 1.7.5]). Let  $X = Y = \{1, 2, \dots\}$  with  $\mathcal{A} = \mathcal{B}$  = all subsets and  $\mu_1 = \mu_2$  = counting measure. let

$$f(m, n) = \begin{cases} 1 & m = n \\ -1 & m = n + 1 \\ 0 & \text{o.w} \end{cases}$$

Then,

$$\int_X \int_Y f(x, y) \mu_2(dy) \mu_1(dx) = 0 \quad \text{but} \quad \int_Y \int_X f(x, y) \mu_1(dx) \mu_2(dy) = 1.$$

$$\begin{array}{cccccc} \vdots & \vdots & \vdots & \vdots & & \\ 0 & 0 & 0 & 1 & \dots & \\ \uparrow & 0 & 0 & 1 & -1 & \dots \\ n & 0 & 1 & -1 & 0 & \dots \\ & 1 & -1 & 0 & 0 & \dots \\ & & & m & \rightarrow & \end{array}$$

**Example** ([1, Example 1.7.6]). Let  $X = (0, 1)$ ,  $Y = (1, \infty)$ , both equipped with the Borel sets and Lebesgue measure. Let  $f(x, y) = e^{-xy} - 2e^{-2xy}$

$$\begin{aligned} \int_0^1 \int_1^\infty f(x, y) dy dx &= \int_0^1 x^{-1} (e^{-x} - e^{-2x}) dx > 0, \\ \int_0^1 \int_1^\infty f(x, y) dy dx &= \int_0^1 x^{-1} (e^{-2x} - e^{-x}) dx < 0. \end{aligned}$$

**Example** ([1, Example 1.7.7]). Let  $X = (0, 1)$  with  $\mathcal{A}$  = the Borel sets and  $\mu_1$  = Lebesgue measure. Let  $Y = (0, 1)$  with  $\mathcal{B}$  = all subsets and  $\mu_2$  = counting measure. Let  $f(x, y) = 1$  if  $x = y$  and 0 otherwise

$$\begin{aligned} \int_Y f(x, y) \mu_2(dy) &= 1 \text{ for all } x \text{ so } \int_X \int_Y f(x, y) \mu_2(dy) \mu_1(dx) = 1, \\ \int_X f(x, y) \mu_1(dx) &= 0 \text{ for all } y \text{ so } \int_Y \int_X f(x, y) \mu_2(dy) \mu_1(dx) = 0. \end{aligned}$$

## Independence (독립)

**Definition.** Let  $(\Omega, \mathcal{F}, P)$  be probability space. Two events  $A, B \in \mathcal{F}$  are independent (독립) if

$$P(A \cap B) = P(A)P(B).$$

Two random variables  $X$  and  $Y$  are independent if for all  $C, D \in \mathcal{R}$ ,

$$P(X \in C, Y \in D) = P(X \in C)P(Y \in D).$$

Two  $\sigma$ -fields  $\mathcal{F}_1$  and  $\mathcal{F}_2$  ( $\subset \mathcal{F}$ ) are independent if for all  $A \in \mathcal{F}_1$  and  $B \in \mathcal{F}_2$ ,  $A$  and  $B$  are independent.

*Remark.* An infinite collection of objects ( $\sigma$ -fields, random variables, or sets) is said to be independent if every finite subcollection is.

**Definition.**  $\sigma$ -fields  $\mathcal{F}_1, \dots, \mathcal{F}_n$  are independent if for all  $A_i \in \mathcal{F}_i$ ,

$$P\left(\bigcap_{i=1}^n A_i\right) = \prod_{i=1}^n P(A_i),$$

Random variables  $X_1, \dots, X_n$  are independent if for all  $B_i \in \mathcal{R}$ ,

$$P\left(\bigcap_{i=1}^n \{X_i \in B_i\}\right) = \prod_{i=1}^n P(X_i \in B_i).$$

Sets  $A_1, \dots, A_n$  are independent if for all  $I \subset \{1, \dots, n\}$ ,

$$P\left(\bigcap_{i \in I} A_i\right) = \prod_{i \in I} P(A_i)$$

*Remark.* the definition of independent events is not enough to assume pairwise independent, which is  $P(A_i \cap A_j) = P(A_i)P(A_j)$ ,  $i \neq j$ . It is clear that independent events are pairwise independent, but converse is not true.

**Example.** Let  $X_1, X_2, X_3$  be independent random variables with  $P(X_i = 0) = P(X_i = 1) = \frac{1}{2}$ . Let  $A_1 = \{X_2 = X_3\}$ ,  $A_2 = \{X_3 = X_1\}$  and  $A_3 = \{X_1 = X_2\}$ . These events are pairwise independent but not independent.

**Theorem** ([1, Theorem 2.1.7]). Suppose  $\mathcal{A}_1, \dots, \mathcal{A}_n$  are independent and  $\mathcal{A}_i$  are  $\pi$ -systems. Then  $\sigma(\mathcal{A}_1), \dots, \sigma(\mathcal{A}_n)$  are independent.

**Theorem** ([1, Theorem 2.1.8]).  $(X_1, \dots, X_n)$  are independent if and only if for all  $x_i \in (-\infty, \infty]$ ,

$$P(X_1 \leq x_1, \dots, X_n \leq x_n) = \prod_{i=1}^n P(X_i \leq x_i)$$

**Theorem** ([1, Theorem 2.1.9]). Suppose  $\mathcal{F}_{i,j}$ ,  $1 \leq i \leq n$ ,  $1 \leq j \leq m(i)$  are independent and let  $\mathcal{G}_i = \sigma(\bigcup_j \mathcal{F}_{i,j})$ . Then  $\mathcal{G}_1, \dots, \mathcal{G}_n$  are independent.

**Theorem** ([1, Theorem 2.1.10]). If for  $1 \leq i \leq n$ ,  $1 \leq j \leq m(i)$ ,  $X_{i,j}$  are independent and  $f_i : \mathbb{R}^{m(i)} \rightarrow \mathbb{R}$  are measurable then  $f_i(X_{i,1}, \dots, X_{i,m(i)})$  are independent.

**Theorem** ([1, Theorem 2.1.11]). Suppose  $X_1, \dots, X_n$  are independent random variables and  $X_i$  has distribution  $\mu_i$ . Then  $(X_1, \dots, X_n)$  has distribution  $\mu_1 \times \dots \times \mu_n$ .

**Theorem** ([1, Theorem 2.1.12]). Suppose  $X$  and  $Y$  are independent and have distribution  $\mu$  and  $\nu$ . If  $h : \mathbb{R}^2 \rightarrow \mathbb{R}$  is a measurable function with  $h \geq 0$  or  $E|h(X, Y)| < \infty$ , then

$$\mathbb{E}h(X, Y) = \int \int h(x, y) d\mu(x) d\nu(y).$$

In particular, when  $h(x, y) = f(x)g(y)$  with  $f, g \geq 0$  or  $\mathbb{E}|f(X)|, \mathbb{E}|g(Y)| < \infty$ , then

$$\mathbb{E}_P[f(X)g(Y)] = \mathbb{E}_P[f(X)]\mathbb{E}_P[g(Y)].$$

**Theorem** ([1, Theorem 2.1.13]). If  $X_1, \dots, X_n$  are independent and have (a)  $X_i \geq 0$  for all  $i$ , or  $\mathbb{E}|X_i| < \infty$  for



all  $i$ , then

$$\mathbb{E} \left( \prod_{i=1}^n X_i \right) = \prod_{i=1}^n \mathbb{E} X_i.$$

**Example** ([1, Exercise 2.1.14]). It can happen that  $\mathbb{E}(XY) = \mathbb{E}X \cdot \mathbb{E}Y$  with  $X$  and  $Y$  are dependent. Suppose joint distribution of  $X$  and  $Y$  is given by the following table:

		$Y$			
		1	0	-1	
$X$	1	0	$a$	0	
	0	$b$	$c$	$b$	
	-1	0	$a$	0	

where  $a, b > 0$ ,  $c \geq 0$  and  $2a + 2b + c = 1$ . Then  $E(XY) = 0 = EXEY$  but

$$P(X = 1, Y = 1) = 0 < ab = P(X = 1)P(Y = 1).$$

**Definition.** Two random variables  $X$  and  $Y$  with  $\mathbb{E}X^2, \mathbb{E}Y^2 < \infty$  that have  $\mathbb{E}XY = \mathbb{E}X\mathbb{E}Y$  are said to be uncorrelated.

**Theorem** ([1, Theorem 2.1.15]). If  $X$  and  $Y$  are independent,  $F(x) = P(X \leq x)$ , and  $G(y) = P(Y \leq y)$ , then

$$P(X + Y \leq z) = \int F(z - y) dG(y)$$

The integral on the right-hand side is called the convolution of  $F$  and  $G$  and is denoted  $F * G(z)$

**Theorem** ([1, Theorem 2.1.16]). Suppose  $X$  with density  $f$  and  $Y$  with distribution function  $G$  are independent. Then  $X + Y$  has density

$$h(x) = \int f(x - y) dG(y)$$

When  $Y$  has density  $g$ , the last formula can be written as

$$h(x) = \int f(x - y) g(y) dy$$

Now, we consider constructing independent random variables.

## [1] finite many random variables

Objective : Construct  $n$  many independent random variables whose distributions are  $F_i$ ,  $i = 1, \dots, n$

Let  $\Omega = \mathbb{R}^n$ ,  $\mathcal{F} = \mathcal{R}^n$  and  $X_i(\omega) = X_i(\omega_1, \dots, \omega_n) = \omega_i$ . Then we let

$$P([a_1, b_1] \times \dots \times [a_n, b_n]) = \prod_{i=1}^n (F_i(b_i) - F_i(a_i)).$$

## [2] Countably many random variables

Notation.  $\Omega = \mathbb{R}^{\mathbb{N}} = \{(\omega_1, \omega_2, \dots) \mid \omega_i \in \mathbb{R}\}$

$\mathcal{B}(\mathbb{R}^{\mathbb{N}}) = \mathcal{R}^{\mathbb{N}}$  : the smallest  $\sigma$ -fields generated by collection of finite dimensional rectangles  $\{\omega \mid \omega_i \in B_i, B_i \in \mathcal{R}, i = 1, \dots, n\}$   $n = 1, 2, \dots$

We want to specify  $P$  on  $(\mathbb{R}^{\mathbb{N}}, \mathcal{R}^{\mathbb{N}})$  by specifying  $P$  on finite dimensional rectangles

**Theorem** ([1, Theorem 2.1.21]). *Kolmogorov's extension theorem. Suppose we are given probability measures  $\mu_n$  on  $(\mathbb{R}^n, \mathcal{R}^n)$  that are consistent, that is,*

$$\mu_{n+1}((a_1, b_1] \times \cdots \times (a_n, b_n] \times \mathbb{R}) = \mu_n((a_1, b_1] \times \cdots \times (a_n, b_n]).$$

*Then, there is a unique probability measure  $P$  on  $(\mathbb{R}^{\mathbb{N}}, \mathcal{R}^{\mathbb{N}})$  with*

$$P(\omega : \omega_i \in (a_i, b_i], 1 \leq i \leq n) = \mu_n((a_1, b_1] \times \cdots \times (a_n, b_n]).$$

## Weak laws of large numbers (큰 수의 약법칙)

### Various modes of convergence

$\{X_n\}$  and  $X$  are random variables defined on  $(\Omega, \mathcal{F}, P)$

**Definition.**  $X_n \rightarrow X$  almost surely (a.s.) ( with probability 1(w.p. 1), almost everywhere(a.e.) ) if  $P\{\omega : X_n(\omega) \rightarrow X(\omega)\} = 1$

Equivalent definition :  $\forall \epsilon, \lim_{m \rightarrow \infty} P\{\omega : |X_n(\omega) - X(\omega)| \leq \epsilon \forall n \geq m\} = 1$   
or  $\forall \epsilon, \lim_{m \rightarrow \infty} P\{\omega : |X_n(\omega) - X(\omega)| > \epsilon \forall n \geq m\} = 0$

**Definition.**  $X_n \rightarrow X$  in probability (확률수렴) (in pr,  $\xrightarrow{p}$ ) if  $\lim_{n \rightarrow \infty} P\{|X_n - X| > \epsilon\} = 0$

**Theorem.**  $X_n \rightarrow X$  a.s.  $\implies X_n \xrightarrow{p} X$

*Remark.*  $X_n \xrightarrow{p} X \not\Rightarrow X_n \rightarrow X$  a.s.

**Definition.**  $X_n \rightarrow X$  in  $L_p$ ,  $0 < p < \infty$   
if  $\lim_{n \rightarrow \infty} E(|X_n - X|^p) = 0$  provided  $E|X_n|^p < \infty$ ,  $E|X|^p < \infty$ .

**Theorem.**  $X_n \rightarrow X$  in  $L_p \implies X_n \xrightarrow{p} X$

**Theorem.** (Chebyshev inequality, 체비셰프 부등식)

$$P(|X| \geq \epsilon) \leq \frac{E|X|^p}{\epsilon^p}$$

*Remark.*  $X_n \xrightarrow{p} X \not\Rightarrow X_n \rightarrow X$  in  $L_p$

**Example.**  $\Omega = [0, 1]$ ,  $\mathcal{F} = \mathcal{B}[0, 1]$ ,  $P = \text{Unif}[0, 1]$

$$X(\omega) = 0, X_n(\omega) = nI(0 \leq \omega \leq \frac{1}{n})$$

$$\text{Then } P\{|X_n(\omega) - X(\omega)| > \epsilon\} = P\{0 \leq \omega \leq \frac{1}{n}\} = \frac{1}{n} \rightarrow 0$$

$$\text{But } E|X_n - X| = E|X_n| = 1$$

**Theorem.**  $X_n \xrightarrow{p} X$  and there exists a random variables  $Z$  s.t.

$$|X_n| \leq Z \text{ and } E|Z|^p < \infty$$

Then  $X_n \rightarrow X$  in  $L_p$ .

*Remark.* If  $E|X| < \infty$ , then

$$\lim_{n \rightarrow \infty} \int_{A_n} |X| dP \rightarrow 0 \text{ whenever } P(A_n) \rightarrow 0$$

## $L_2$ weak law

**Theorem** ([1, Theorem 2.2.3]). Let  $X_1, X_2, \dots$  be uncorrelated random variables with  $EX_i = \mu$  and  $\text{Var}(X_i) \leq C < \infty$ . Let  $S_n = \sum_{i=1}^n X_i$ . Then  $\frac{S_n}{n} \rightarrow \mu$  in  $L_2$  and also in probability.

**Theorem** ([1, Theorem 2.2.14]). Weak law of large numbers (큰 수의 약법칙, 대수의 약법칙)

Let  $X_1, X_2, \dots$  be i.i.d. random variables with  $E|X_i| < \infty$ . Let  $S_n = X_1 + \dots + X_n$  and let  $\mu = EX_1$ . Then  $\frac{S_n}{n} \rightarrow \mu$  in probability.

## Borel-Canteli lemma

Let  $\{A_n\}$  be a sequence of subsets of  $\Omega$ .

**Definition.**  $\limsup A_n = \lim_{m \rightarrow \infty} \bigcup_{n=m}^{\infty} A_n = \{\omega \text{ that are in infinitely many } A_n\} = \{A_n \text{ i.o.}\}$

$\liminf A_n = \lim_{m \rightarrow \infty} \bigcap_{n=m}^{\infty} A_n = \{\omega \text{ that are in all but finite } A_n\} = \{A_n \text{ a.b.f.}\}$

**Theorem** ([1, Theorem 2.3.1]). Borel-Canteli lemma (보렐-칸텔리 보조정리)

If  $\sum_{n=1}^{\infty} P(A_n) < \infty$ , then

$$P(A_n \text{ i.o.}) = 0.$$

**Theorem** ([1, Theorem 2.3.2]).  $X_n \rightarrow X$  in probability (확률수렴) if and only if for every subsequence  $X_{n(m)}$ , there is a further subsequence  $X_{n(m_k)}$  that converges almost surely to  $X$ .

**Theorem** ([1, Theorem 2.3.3]). For a given sequence  $\{y_n\}$  of a topological space, if any subsequence  $y_{n(m)}$  has a convergent subsequence  $y_{n(m_k)}$  which converges to  $y$ , then  $y_n \rightarrow y$

**Theorem** ([1, Theorem 2.3.4]). If  $f$  is continuous and  $X_n \rightarrow X$  in probability (확률수렴), then  $f(X_n) \rightarrow f(X)$  in probability (확률수렴). If in addition  $f$  is bounded, then  $\mathbb{E}f(X_n) \rightarrow \mathbb{E}f(X)$ .

**Theorem** ([1, Theorem 2.3.5]). Let  $\{X_n\}$  be i.i.d. random variables with  $E(X_n) = \mu$  and  $EX_1^4 < \infty$ . If  $S_n = \sum_{i=1}^n X_i$  then  $\frac{S_n}{n} \rightarrow \mu$  a.s..

**Example** ([1, Example 2.3.6]).  $\Omega = [0, 1]$   $\mathcal{F} = \mathcal{B}[0, 1]$ ,  $P \sim \text{unif}(0, 1)$ . Let  $A_n = (0, \frac{1}{n})$ , then  $P(A_n \text{ i.o.}) = 0$  but  $\sum P(A_n) = \infty$ .

**Theorem** ([1, Theorem 2.3.7]). The second Borel Cantelli lemma

If  $A_n$  are independent, then  $\sum P(A_n) = \infty$  implies that

$$P(A_n \text{ i.o.}) = 1.$$

**Theorem** ([1, Theorem 2.3.8]). Let  $X_n$  be i.i.d. random variables with  $E|X_1| = \infty$ , then  $P\{|X_n| \geq n \text{ i.o.}\} = 1$ . So if  $S_n = X_1 + \dots + X_n$ , then

$$P\left(\lim_{n \rightarrow \infty} \frac{S_n}{n} \in (-\infty, \infty)\right) = 0.$$

## Strong Law of Large Numbers (큰 수의 강법칙)

**Theorem** ([1, Theorem 2.4.1]). Let  $X_1, X_2, \dots$  be pairwise independent and identically distributed random variables with  $E|X_1| < \infty$ . Let  $\mu = E(X_1)$  and  $S_n = \sum_{i=1}^n X_i$ . Then  $\frac{S_n}{n} \rightarrow \mu$  a.s..

**Theorem** ([1, Theorem 2.4.5]). Let  $X_1, X_2, \dots$  be i.i.d. with  $EX_i^+ = \infty$  and  $EX_1^- < \infty$ . If  $S_n = X_1 + \dots + X_n$  then  $\frac{S_n}{n} \rightarrow \infty$  a.s.

**Example** ([1, Example 2.4.8]). Empirical distribution functions

Let  $X_1, X_2, \dots \stackrel{iid}{\sim} F$ , and let

$$F_n(x) = \frac{1}{n} \sum_{i=1}^n I(X_i \leq x).$$

- 1) For given  $x$ ,  $E(F_n(x)) = F(x)$  unbiased
- 2) For given  $x$ ,  $F_n(x) \rightarrow F(x)$  consistency
- 3) asymptotic efficient?

**Theorem** ([1, Theorem 2.4.9]). *Glivenko-Cantelli theorem (글리벤코-칸텔리 정리)*

$$\sup_x |F_n(x) - F(x)| \rightarrow 0 \text{ a.s. as } n \rightarrow \infty.$$

## Weak Convergence

We define weak convergence for random variables, but most of the results can be generalized to measurable maps  $X_n, X : (\Omega, \mathcal{F}) \rightarrow (S, \mathcal{S})$ , where  $S$  is equipped with a metric  $\rho$ .

**Definition.** A sequence of random vectors  $\{X_n\}$  converges weakly or converges in distribution (분포수렴) to a limit  $X$  ( $X_n \Rightarrow X$ ,  $X_n \xrightarrow{w} X$ ,  $X_n \xrightarrow{d} X$ ) if

$$\mathbb{E}_P[g(X_n)] \rightarrow \mathbb{E}_P[g(X)], \quad \text{for all } g \in C_b(\mathbb{R}),$$

where  $C_b(\mathbb{R})$  is a set of continuous and bounded functions. We analogously define  $P_n \xrightarrow{d} P$  for probability measures  $\{P_n\}$  and  $P$ , i.e.,  $\int g(x)dP_n(x) \rightarrow \int g(x)dP(x)$  for all  $g \in C_b(\mathbb{R})$ . We also analogously define  $F_n \xrightarrow{d} F$  ( $F_n \Rightarrow F$ ,  $F_n \xrightarrow{w} F$ ) for distribution functions  $\{F_n\}$  and  $F$ , i.e.,  $\int g(x)dF_n(x) \rightarrow \int g(x)dF(x)$  for all  $g \in C_b(\mathbb{R})$ .

**Theorem** ([1, Theorem 3.2.9]). A sequence of distribution function  $F_n$  converges weakly to a limit  $F$  if and only if  $F_n(y) \rightarrow F(y)$  for all continuity points of  $F$ .

**Example** ([1, Example 3.2.1]). Let  $X_1, X_2, \dots$  be i.i.d. with  $P(X_1 = 1) = P(X_1 = -1) = \frac{1}{2}$ , and let  $S_n = X_1 + \dots + X_n$ . Then

$$F_n(y) = P(S_n/\sqrt{n} \leq y) \rightarrow \int_{-\infty}^y \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \quad \forall y \in \mathbb{R}.$$

That is,  $F_n \xrightarrow{w} \mathcal{N}(0, 1)$ .

**Example** ([1, Example 3.2.3]). Let  $X \sim F$  and  $X_n = X + \frac{1}{n}$ . Then

$$F_n(x) = P(X_n \leq x) = F(x - \frac{1}{n}) \rightarrow F(x-).$$

Hence  $F_n(x) \rightarrow F(x)$  only when  $F(x) = F(x-)$ , i.e. only if  $x$  is a continuity point of  $F$ . Still,  $X_n \xrightarrow{d} X$ .

**Example** ([1, Example 3.2.4]). Let  $X_p \sim \text{Geo}(p)$ , i.e.  $P(X_p \geq m) = (1-p)^{m-1}$ . Then

$$P(X_p > \frac{x}{p}) = (1-p)^{\frac{x}{p}} \rightarrow e^{-x}, \quad \text{as } p \rightarrow 0.$$

In words,  $pX_p$  converges weakly to an exponential distribution.

**Theorem.** *Scheffe's theorem. Let  $\{f_n\}$  be a sequence of densities and let  $f_\infty$  be a density. If  $f_n \rightarrow f_\infty$  pointwisely, then*

$$\|\mu_n - \mu_\infty\|_{TV} := \sup_B |\mu_n(B) - \mu_\infty(B)| \rightarrow 0,$$

when  $\mu_n$  and  $\mu_\infty$  are probability measure corresponding to  $f_n$  and  $f_\infty$ .

$\|\mu_n - \mu_\infty\|_{TV}$  is called the total variation norm. If  $\mu_n \rightarrow \mu_\infty$  in the total variation norm, then  $\mu_n \xrightarrow{w} \mu_\infty$  (i.e.  $F_n \xrightarrow{w} F_\infty$ ) However, the converse is not true.

**Theorem** ([1, Theorem 3.2.8]). *(Skorohod representation theorem)*

Suppose  $F_n \xrightarrow{d} F$ . Then, there exists a probability space  $(\Omega, \mathcal{F}, P)$ , a sequence of random variables  $\{Y_n\}$  and a random variables  $Y$  on  $(\Omega, \mathcal{F}, P)$  so that  $Y_n \sim F_n$ ,  $Y \sim F$ , and  $Y_n \rightarrow Y$  a.s..

**Theorem** ([1, Theorem 3.2.10]). *Continuous mapping theorem.*

Let  $g$  be a measurable function and  $D_g = \{x : g \text{ is continuous at } x\}$ . If  $X_n \xrightarrow{d} X$  and  $P(X \in D_g) = 0$ , then  $g(X_n) \xrightarrow{d} g(X)$ . If in addition  $g$  is bounded, then  $\mathbb{E}g(X_n) \rightarrow \mathbb{E}g(X)$ .

**Theorem** ([1, Theorem 3.2.11]). *The following statements are equivalent*

- (i)  $X_n \xrightarrow{d} X$
- (ii)  $\forall \text{ open set } G, \liminf P(X_n \in G) \geq P(X \in G)$
- (iii)  $\forall \text{ closed set } G, \limsup P(X_n \in G) \leq P(X \in G)$
- (iv) For all set  $A$  with  $P(X \in \partial A) = 0$ ,  $\lim P(X_n \in A) = P(X \in A)$ , where  $\partial A = clA - intA$ .

**Theorem** ([1, Theorem 3.2.12]). *Helly's selection theorem*

For every sequence  $F_n$  of distribution functions, there exists a subsequence  $F_{n(k)}$  and a right continuous nondecreasing function  $F$  so that

$$F_{n(k)}(y) \rightarrow F(y), \quad \text{for all continuity points } y \text{ of } F.$$

*Remark.* The limit may not be a distribution function.

**Theorem** ([1, Theorem 3.2.13]). *Every subsequential limit of Helly's selection theorem is a distribution function if and only if the sequence  $F_n$  is tight, i.e., for all  $\epsilon > 0$  there exists  $M_\epsilon > 0$  so that*

$$\limsup_{n \rightarrow \infty} \{1 - F_n(M_\epsilon) + F_n(-M_\epsilon)\} \leq \epsilon.$$

.

**Theorem** ([1, Theorem 3.2.14]). *If there is a  $\varphi \geq 0$  so that  $\varphi(x) \rightarrow \infty$  as  $|x| \rightarrow \infty$  and*

$$C = \sup_n \int \varphi(x) dF_n(x) < \infty,$$

then  $F_n$  is tight.

**Exercise** ([1, Theorem 3.2.15]). Lévy metric for cumulative distribution functions is

$$\rho(F, G) = \inf \{ \epsilon : F(x - \epsilon) - \epsilon \leq G(x) \leq F(x + \epsilon) + \epsilon \text{ for all } x \in \mathbb{R} \}.$$

Then  $\rho(F_n, F) \rightarrow 0$  if and only if  $F_n \xrightarrow{d} F$ . So, convergence in distribution can be thought as convergence in metric space.

The fact that convergence in distribution comes from a metric immediately implies

**Theorem** ([1, Theorem 3.2.15]). *If each subsequence of  $X_n$  has a further subsequence that converges to  $X$  then  $X_n \xrightarrow{d} X$ .*

## Characteristic Functions

**Definition.** The characteristic function (ch.f.) of a random variable  $X$  is defined by

$$\varphi(t) = \mathbb{E}e^{itX} = E(\cos(tX)) + iE(\sin(tX))$$

**Theorem** ([1, Theorem 3.3.1]). *All characteristic functions have the following properties:*

- (a)  $\varphi(0) = 1$
- (b)  $\varphi(-t) = \overline{\varphi(t)}$ , where  $\bar{z} = a - bi$  if  $z = a + bi$
- (c)  $|\varphi(t)| \leq 1$
- (d)  $\varphi(t)$  is uniformly continuous on  $(-\infty, \infty)$
- (e)  $\mathbb{E}e^{it(aX+b)} = e^{itb}\varphi(at)$

**Theorem** ([1, Theorem 3.3.2]). *If  $X_1$  and  $X_2$  are two independent random variables with the ch.f.  $\varphi_1$  and  $\varphi_2$ , then  $X_1 + X_2$  has the ch.f.  $\varphi_1(t) \cdot \varphi_2(t)$*

**Theorem** ([1, Theorem 3.3.11]). *Inversion formula.*

*Let  $\varphi(t) = \int e^{itx} \mu(dx)$ , where  $\mu$  is a probability measure. If  $a < b$ , then*

$$\lim_{T \rightarrow \infty} \frac{1}{2\pi} \int_{-T}^T \frac{e^{-ita} - e^{-itb}}{it} \varphi(t) dt = \mu(a, b) + \frac{1}{2} \mu\{a, b\}.$$

**Theorem** ([1, Theorem 3.3.14]). *If  $\int |\varphi(t)| dt < \infty$ , then  $\mu$  has bounded continuous density  $f$  so that*

$$f(y) = \frac{1}{2\pi} \int e^{-ity} \varphi(t) dt.$$

**Theorem** ([1, Theorem 3.3.17]). *Let  $\mu_n$  be a sequence of probability measures with the ch.f.s  $\{\varphi_n\}$ .*

- (i) *If  $\mu_n \Rightarrow \mu_\infty$ , then  $\varphi_n(t) \rightarrow \varphi_\infty(t)$  for all  $t$*
- (ii) *Suppose  $\varphi_n(t) \rightarrow \varphi(t)$  pointwisely. If  $\varphi$  is continuous at 0, then the associated distributions  $\mu_n$  is tight, and converges weakly to the probability measure  $\mu_\infty$  with the ch.f.  $\varphi$ .*

*Remark.* The continuity of  $\varphi$  at 0 implies that that  $\mu_\infty$  is a probability measure.

## Central Limit Theorem (중심극한정리)

**Theorem** ([1, Theorem 3.4.1]). *Let  $X_1, X_2, \dots$  be i.i.d. with  $\mathbb{E}X_i = \mu$  and  $\text{Var}(X_i) = \sigma^2 > 0$ . If  $S_n = X_1 + \dots + X_n$ , then*

$$(S_n - n\mu)/(\sqrt{n}\sigma) \xrightarrow{d} \mathcal{N}(0, 1).$$

**Theorem** ([1, Theorem 3.4.10]). *Lindeberg-Feller theorem*

*For each  $n$ , let  $X_{n,m}$ ,  $1 \leq m \leq n$ , be independent random variables with  $\mathbb{E}X_{n,m} = 0$ . Suppose*

- (i)  $\sum_{m=1}^n \mathbb{E}X_{n,m}^2 \rightarrow \sigma^2 > 0$ ,
- (ii)  $\forall \epsilon > 0, \lim_{n \rightarrow \infty} \sum_{m=1}^n \mathbb{E}(|X_{n,m}|^2 I(|X_{n,m}| > \epsilon)) = 0$ .

*Then  $S_n = X_{n,1} + \dots + X_{n,n} \xrightarrow{d} \mathcal{N}(0, \sigma^2)$  as  $n \rightarrow \infty$ .*

*Remark.* We can prove the first CLT using the Lindeberg-Feller theorem.

**Exercise** ([1, Exercise 3.4.12]). Lyapunov's theorem

Let  $\{X_{n,m}\}$  be a triangular array of independent random variables satisfying

(i)  $\mathbb{E}|X_{n,m}|^{2+\delta} < \infty$  for some  $\delta > 0$

(ii)  $\lim_{n \rightarrow \infty} \sum_{m=1}^n \mathbb{E}|X_{n,m} - \mathbb{E}X_{n,m}|^{2+\delta} / s_n^{2+\delta} = 0$ , where  $s_n^2 = \text{Var}(S_n)$

Then  $(S_n - \mathbb{E}S_n) / \sqrt{s_n^2} \xrightarrow{d} \mathcal{N}(0, 1)$ .

**Theorem.** (Feller)

Let  $\{X_{n,k}\}$  be an array of independent random variables.

Lindeberg's condition holds if and only if CLT holds and  $\max_{1 \leq k \leq n} \sigma_{nk}^2 / s_n^2 \rightarrow 0$  as  $n \rightarrow \infty$ .

**Theorem** ([1, Theorem 3.4.14]). Let  $X_1, X_2, \dots$  be i.i.d. and  $S_n = X_1 + \dots + X_n$ . Then there exist  $a_n, b_n > 0$  so that  $(S_n - a_n) / b_n \xrightarrow{d} \mathcal{N}(0, 1)$  if and only if

$$y^2 P(|X_1| > y) / \mathbb{E}(|X_1|^2; |X_1| \leq y) \rightarrow 0$$

**Theorem** ([1, Theorem 3.4.17]). Berry-Essen theorem

Let  $X_1, X_2, \dots$  be i.i.d. with  $\mathbb{E}X_i = 0$ ,  $\mathbb{E}X_i^2 = \sigma^2$  and  $\mathbb{E}|X_1|^3 = \rho < \infty$ . Let  $F_n(x)$  be the distribution function of  $(X_1 + \dots + X_n) / (\sigma\sqrt{n})$  and  $\Phi(x)$  be the standard normal distribution. Then

$$\sup_x |F_n(x) - \Phi(x)| \leq 3\rho / (\sigma^3 \sqrt{n}).$$

## Stochastic Order Notation

The classical order notation should be familiar to you already.

1. We say that a sequence  $a_n = o(1)$  if  $a_n \rightarrow 0$  as  $n \rightarrow \infty$ . Similarly,  $a_n = o(b_n)$  if  $a_n/b_n = o(1)$ .
2. We say that a sequence  $a_n = O(1)$  if the sequence is eventually bounded, i.e. for all  $n$  large,  $|a_n| \leq C$  for some constant  $C \geq 0$ . Similarly,  $a_n = O(b_n)$  if  $a_n/b_n = O(1)$ .
3. If  $a_n = O(b_n)$  and  $b_n = O(a_n)$  then we use either  $a_n = \Theta(b_n)$  or  $a_n \asymp b_n$ .

When we are dealing with random variables we use stochastic order notation.

1. We say that  $X_n = o_P(1)$  if for every  $\epsilon > 0$ , as  $n \rightarrow \infty$

$$\mathbb{P}(|X_n| \geq \epsilon) \rightarrow 0,$$

i.e.  $X_n$  converges to zero in probability.

2. We say that  $X_n = O_P(1)$  if for every  $\epsilon > 0$  there is a finite  $C(\epsilon) > 0$  such that, for all  $n$  large enough:

$$\mathbb{P}(|X_n| \geq C(\epsilon)) \leq \epsilon.$$

The typical use case: suppose we have  $X_1, \dots, X_n$  which are i.i.d. and have finite variance, and we define:

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n X_i.$$

1.  $\hat{\mu} - \mu = o_P(1)$  (Weak Law of Large Number)

2.  $\hat{\mu} - \mu = O_P(1/\sqrt{n})$  (Central Limit Theorem)

**Proposition.** 1.  $X_n \xrightarrow{P} X$  implies  $X_n \xrightarrow{d} X$ , and this implies  $X_n = O_p(1)$ . Also,  $X_n = o_p(1)$  implies  $X_n = O_p(1)$ .

2. (a)  $O_p(1) + O_p(1) = O_p(1)$

(b)  $O_p(1) + o_p(1) = O_p(1)$

(c)  $o_p(1) + o_p(1) = o_p(1)$

(d)  $O_p(1) \cdot O_p(1) = O_p(1)$

(e)  $O_p(1) \cdot o_p(1) = o_p(1)$

(f)  $o_p(1) \cdot o_p(1) = o_p(1)$

## References

- [1] Rick Durrett. *Probability—theory and examples*, volume 49 of *Cambridge Series in Statistical and Probabilistic Mathematics*. Cambridge University Press, Cambridge, 2019. Fifth edition.